

THE ASYMPTOTIC BEHAVIOR OF THE SOLUTIONS OF LINEAR AND NONLINEAR DIFFERENTIAL- DIFFERENCE EQUATIONS

BY

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1. Introduction. We intend in this paper to discuss the solutions of linear functional equations of the form

$$(1.1) \quad \frac{d}{dt} u(t+1) = a(t)u(t) + b(t)u(t+1)$$

and nonlinear equations of the form

$$(1.2) \quad \frac{d}{dt} u(t+1) = a(t)u(t) + b(t)u(t+1) + D(u(t), u(t+1)),$$

where

$$(1.3) \quad D(u(t), u(t+1)) = \sum_{i+j \geq 2} b_{ij}(t)u(t)^i u(t+1)^j \quad (i \geq 0, j \geq 0),$$

where $a(t)$, $b(t)$, and the $b_{ij}(t)$ are given real functions of the real variable t . We seek to find real functions $u(t)$ which satisfy (1.1) or (1.2) for $t > t_0$ ($t_0 > 0$), and which satisfy the boundary condition $u(t) = g(t)$ for $t_0 \leq t \leq t_0 + 1$, where $g(t)$ is a given real continuous function. The principal aim of this paper is to characterize such solutions for large positive values of the independent variable.

Consider, for the moment, the more general linear equation

$$\frac{d^n}{dt^n} u(t) + \sum_{k=0}^{n-1} \sum_{i=1}^n c_{ik}(t) \frac{d^k}{dt^k} u(t - t_i) = 0,$$

where $0 < t_1 < t_2 < \cdots < t_n$. As observed by Bellman [2], this equation is a special case of the system which, in vector-matrix notation, is

$$\frac{d}{dt} u(t) = A_0(t)u(t) + A_1(t)u(t - t_1) + \cdots + A_n(t)u(t - t_n),$$

where u is an n -dimensional column vector and A_k is a square matrix with n

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columns. The boundary condition is $u = g(t)$ for $0 \leq t \leq t_n$, where $g(t)$ is a given vector function. The methods to be employed below could be extended to provide information concerning this general equation and an associated non-linear equation. However, in order to avoid extraneous complications, the discussion will be restricted to the first order equations (1.1) and (1.2).

Functional equations of the above type occur in several branches of mathematical physics. For references, see Hoheisel [8], Hilb [7], and Wright [17]. Very complete information on the solutions of equations with constant coefficients has been obtained by Schmidt [11], Hilb [7], Titchmarsh [12], Pitt [10], Wright [14; 15; 17; 18], and Brownell [4], but much less is known if the coefficients are not constant. However, Bellman [2] and Wright [16] have obtained important results concerning differential-difference equations in which the coefficients, while not constants, have constant limits as t tends to $+\infty$. In this paper, we suppose that $a(t)$ and $b(t)$ have asymptotic expansions

$$(1.4) \quad a(t) \sim a_0 + \frac{a_1}{t} + \frac{a_2}{t^2} + \cdots, \quad b(t) \sim b_0 + \frac{b_1}{t} + \frac{b_2}{t^2} + \cdots,$$

as $t \rightarrow +\infty$, and we seek to determine the behavior of the solutions of (1.1) and (1.2) as $t \rightarrow +\infty$. This subject is suggested by the discussion of the analogous problem for differential equations and for difference equations carried out by various authors. See, for example, Hukuhara [9] and Trjitzinsky [13], where references to related papers are given.

Before beginning the detailed study of (1.1) and (1.2), we shall briefly indicate the method to be used and the conclusions reached. Throughout this article, the equation

$$(1.5) \quad se^s - b_0 e^s - a_0 = 0$$

is called the *characteristic equation*, and its roots are called the *characteristic roots*. The first step in studying (1.1) or (1.2), where $a(t)$ and $b(t)$ have the asymptotic expansions (1.4), is to investigate the *equation of first approximation*

$$(1.6) \quad \frac{d}{dt} u(t+1) = \left(a_0 + \frac{a_1}{t}\right) u(t) + \left(b_0 + \frac{b_1}{t}\right) u(t+1),$$

subject to the prescribed boundary condition. By use of the Laplace transform, we may express the solution of (1.6) as a contour integral. The asymptotic behavior of the solution can then be determined by a familiar method. The principal conclusions may be stated as follows.

THEOREM 1.1. *There is a unique function $u(t)$ which satisfies the equation (1.6) above for $t > t_0$ and which satisfies the boundary condition*

$$(1.7) \quad u(t) = g(t) \quad (t_0 \leq t \leq t_0 + 1),$$

where $g(t)$ is an arbitrary real continuous function and a_0, a_1, b_0 , and b_1 are any real constants. If $a_0 \neq -\exp(b_0 - 1)$, there is one particular characteristic root S_2 , which depends on a_0, a_1, b_0, b_1 , and $g(t)$, and there are constants $c_0, c_1, c_2, \dots, c_m \neq 0$, such that, given any positive integer m ,

$$(1.8) \quad u(t+1) = \operatorname{Re} \left\{ t^{\delta_2} e^{S_2 t} \left(c_0 + \frac{c_1}{t} + \dots + \frac{c_m}{t^m} \right) \right\} + O(t^{\operatorname{Re}(\delta_2) - m - 1} e^{\operatorname{Re}(S_2)t})$$

as $t \rightarrow +\infty$, where δ_2 is the residue of

$$(1.9) \quad \frac{a_1 e^{-s} + b_1}{s - b_0 - a_0 e^{-s}}$$

at S_2 .

Theorem 1.1 is basic in the discussion of the more general equations (1.1) and (1.2), and is, perhaps, of some intrinsic interest. §2 of this essay is devoted to the proof of Theorem 1.1. In §3, we consider the *nonhomogeneous equation*

$$(1.10) \quad \frac{d}{dt} u(t+1) = \left(a_0 + \frac{a_1}{t} \right) u(t) + \left(b_0 + \frac{b_1}{t} \right) u(t+1) + w(t).$$

By applying the Laplace transform again, we are able to prove that, under certain conditions on $w(t)$, the solution $u(t)$ of (1.10) which satisfies the boundary condition (1.7) is of the form

$$u(t) = u_0(t) + u_1(t),$$

where $u_0(t)$ is the solution of (1.6) and (1.7), and where $u_1(t)$ may be written in the form

$$u_1(t+1) = \int_{t_0}^t w(t_1) k(t, t_1) dt_1.$$

$k(t, t_1)$ is defined below.

In §4, we discuss the general linear equation (1.1), where $a(t)$ and $b(t)$ have the asymptotic expansions (1.4). We note that (1.1) is of the same form as (1.10), if $w(t)$ is appropriately chosen. The results of §3 therefore suggest the consideration of the linear integral equation

$$(1.11) \quad u(t+1) = u_0(t+1) + \int_{t_0}^t \{ A(t_1) u(t_1) + B(t_1) u(t_1+1) \} k(t, t_1) dt_1,$$

where $A(t) = a(t) - a_0 - a_1/t$ and $B(t) = b(t) - b_0 - b_1/t$. The solution of (1.11) and (1.7) may readily be constructed by the method of successive approximations, and may be shown to be the solution of (1.1). We can then ascertain its asymptotic character with the aid of Theorem 1.1 and the known form of $k(t, t_1)$.

We use a similar procedure in §5 in studying (1.2). Our principal results are as follows:

THEOREM 1.2. *There is a unique function $u(t)$ which satisfies the boundary condition (1.7) and which satisfies the equation (1.1) for $t > t_0$, if $a(t)$ and $b(t)$ have the asymptotic expansions (1.4) as $t \rightarrow +\infty$. Let S_1 be the characteristic root of largest real part⁽²⁾, and let δ_1 be the residue of (1.9) at S_1 . If $a_0 \neq -\exp(b_0 - 1)$,*

$$(1.12) \quad u(t) = O(t^{\operatorname{Re}(\delta_1)} e^{\operatorname{Re}(S_1)t})$$

as $t \rightarrow +\infty$ ⁽³⁾.

COROLLARY. *If $\operatorname{Re}(S_1) < 0$ ⁽⁴⁾, or if $\operatorname{Re}(S_1) = 0$ and $\operatorname{Re}(\delta_1) < 0$, all solutions of (1.1) approach zero as $t \rightarrow +\infty$.*

THEOREM 1.3. *Consider the nonlinear equation (1.2) where $a(t)$ and $b(t)$ have the asymptotic expansions (1.4) as $t \rightarrow +\infty$, and where (1.3) holds for certain real functions $b_{ij}(t)$. Suppose that the following conditions are satisfied:*

- (a) $\operatorname{Re}(S_1) < 0$;
- (b) $|b_{ij}(t)| \leq b_{ij}$, where the b_{ij} are independent of t ;
- (c) $\sum_{i+j \geq 2} b_{ij} z_1^i z_2^j$ converges for $|z_1|$ and $|z_2|$ sufficiently small.

Then there is a constant C , depending on the particular equation (1.2) under consideration, such that if

$$(d) \quad \max_{t_0 \leq t \leq t_0+1} |g(t)| \leq C,$$

then the following conclusions are valid: There is a unique function $u(t)$ which satisfies (1.2) for $t > t_0$ and which satisfies the boundary condition (1.7). $u(t)$ has the form (1.12) as $t \rightarrow +\infty$ ⁽⁵⁾.

2. Proof of Theorem 1.1. Consider the equation

$$(2.1) \quad \frac{d}{dt} u(t+1) = \left(a_0 + \frac{a_1}{t}\right) u(t) + \left(b_0 + \frac{b_1}{t}\right) u(t+1),$$

in which a_0, a_1, b_0, b_1 , and t are all real. We shall, in this section, indicate the method by which Theorem 1.1 may be proved. Since the proof is obtained by standard techniques, we shall omit some of the details. In the first place, it is clear that there is a unique real function $u(t)$ which satisfies (2.1) for $t > t_0$ and which satisfies the boundary condition

$$(2.2) \quad u(t) = g(t) \quad (t_0 \leq t \leq t_0 + 1),$$

⁽²⁾ The existence of S_1 is proved below.

⁽³⁾ The methods herein given can be extended so as to yield an asymptotic series representation.

⁽⁴⁾ Hayes [6] has derived a necessary and sufficient condition in order that all characteristic roots have negative real parts.

⁽⁵⁾ The methods herein given can be extended so as to yield an asymptotic series representation.

where $g(t)$ is a given real continuous function. We shall find the Laplace transform of this solution, and then apply a standard inversion theorem in order to obtain a suitable representation of the solution. An examination of the singularities of the transform will yield the asymptotic results stated in Theorem 1.1.

First of all, it is easily shown by integrating (2.1) and then using a lemma employed extensively by other authors—cf. Bellman [1]—that

$$|u(t+1)| \leq Ct^{|a_1|+|b_1|} e^{(|a_0|+|b_0|)t},$$

and hence that the transform

$$(2.3) \quad U(s, t_0) = \int_{t_0}^{\infty} u(t) e^{-st} dt$$

exists and is an analytic function of s in a certain half-plane. From (2.1), we find that U satisfies the differential equation

$$(2.4) \quad (se^s - b_0 e^s - a_0) U'(s, t_0) + \left[\frac{d}{ds} (se^s - b_0 e^s - a_0) + a_1 + b_1 e^s \right] U(s, t_0) = G(s, t_0)$$

within the half-plane of convergence, where

$$(2.5) \quad G(s, t_0) = -t_0 g(t_0 + 1) e^{-st_0} - (s - b_0) e^s \int_{t_0}^{t_0+1} t g(t) e^{-st} dt \\ + e^s (s + 1 - b_0 + b_1) \int_{t_0}^{t_0+1} g(t) e^{-st} dt.$$

Before solving (2.4), we must make a few preliminary remarks, the first of which concern the characteristic roots, the roots of

$$(2.6) \quad se^s - b_0 e^s - a_0 = 0.$$

Wright [14] proved that in any vertical strip $x_1 \leq \operatorname{Re}(s) \leq x_2$, there are but a finite number of characteristic roots. It is also easily established that if $a_0 \neq -\exp(b_0 - 1)$, all the characteristic roots are simple, and that on any vertical line $\operatorname{Re}(s) = x$, either there is a single root, and it is x , or there are two conjugate complex roots, or there are no roots. Finally, all the roots S are such that $\operatorname{Re}(S) \leq |a_0| + |b_0|$. Thus there is a characteristic root $S_1 = X_1 + iY_1$ with the property that all the characteristic roots lie on the line $\operatorname{Re}(s) = X_1$, or to the left of it.

Let x_0 be an arbitrary real number for which $x_0 > X_1$, and let s be any complex number which is not a characteristic root. Define the function

$$(2.7) \quad h(s) = \int_{x_0, L_1}^s \frac{a_1 e^{-s_1} + b_1}{s_1 - b_0 - a_0 e^{-s_1}} ds_1$$

where L_1 is a contour of the following description. L_1 starts at x_0 and ends at s , and $\operatorname{Re}(s_1) \geq \operatorname{Re}(s)$ all along L_1 . L_1 does not pass through any characteristic root. Furthermore, if $\operatorname{Im}(s) \geq 0$, L_1 passes above all characteristic roots s' for which $\operatorname{Re}(s') > \operatorname{Re}(s)$. If $\operatorname{Im}(s) < 0$, L_1 passes below all characteristic roots s' for which $\operatorname{Re}(s') > \operatorname{Re}(s)$. The function $h(s)$ is thus defined and single-valued except at the characteristic roots. It is not difficult to see that $h(s)$ will, in general, have branch points at the characteristic roots. If s' is any characteristic root and if δ' is the residue of $h'(s)$ at s' ,

$$(2.8) \quad \exp \{h(s)\} = (s - s')^{\delta'} \sum_{n=0}^{\infty} d_n (s - s')^n$$

for s "near s' ." If δ' is a non-negative integer, (2.8) is valid in a circle $|s - s'| \leq C$, but if δ' is a negative integer an expansion of the above form holds only in an annulus $0 < |s - s'| \leq C$. If δ' is not an integer, $\exp \{h(s)\}$ has a branch point at s' , and (2.8) is valid in an annulus $0 < |s - s'| \leq C$, cut along the real axis if s' is real, but along the line joining s' and $\bar{s}'$ if s' is not real. Also, the expansion

$$(2.9) \quad \frac{e^{-h(s)}}{s - b_0 - a_0 e^{-s}} = (s - s')^{-\delta'-1} \sum_{n=0}^{\infty} h_n (s - s')^n$$

is valid in an appropriate neighborhood of s' .

The following inequalities, which may be proved without great difficulty, will be needed below. First, given any $\sigma > X_1$, there are constants C_1 , C_2 , and p such that

$$(2.10) \quad |s - b_0 - a_0 e^{-s}| \geq C_1 |s|, \quad |\exp h(s)| \leq C_2 |s|^p,$$

and

$$|\exp \{-h(s)\}| \leq C_2 |s|^p$$

for $\operatorname{Re}(s) \geq \sigma$. Given any real σ , there are real numbers ρ and C , depending on σ , for which

$$(2.11) \quad |\exp \{h(x_2 + i\omega) - h(x_1 + i\omega)\}| \leq \exp \{(C + Ce^{-x_1})(x_2 - x_1)\}$$

for all x_1 , x_2 , and ω such that $x_2 > x_1 \geq \sigma$ and $|\omega| > \rho$. Finally, from (2.5) we find that

$$(2.12) \quad |G(s, t_0)| \leq Ce^{x(1-t_0)},$$

for $x = \operatorname{Re}(s) \geq \sigma$.

The solution of (2.4) which we require is one which approaches zero as s tends to infinity along the positive real axis. The only such solution is

$$(2.13) \quad U(s, t_0) = \frac{e^{-h(s)}}{se^s - b_0 e^s - a_0} \int_{+\infty+i0, L_2}^s G(s_1, t_0) e^{h(s_1)} ds_1,$$

where L_2 denotes any contour from $+\infty + i0$ to $s = x + iy$ which lies on or to the right of the line of abscissa x . In order to show that this solution does approach zero as s tends to infinity along the real axis, we use the above inequalities. It is necessary to suppose that t_0 is sufficiently large. This is no loss of generality, since we may successively compute the solution in the intervals $(t_0, t_0 + 1), \dots, (t_0 + m, t_0 + m + 1)$, using (2.1) and (2.2), and take as a new initial condition the functional values found for the interval $(t_0 + m, t_0 + m + 1)$.

From (2.13) we can immediately obtain a representation of the solution $u(t)$ of (2.1), using the inversion theorem stated in Doetsch [5, p. 107]. It is necessary to prove only that, if L is the vertical line from $x - i\infty$ to $x + i\infty$,

$$\int_L e^{ts} U(s, t_0) ds$$

is uniformly convergent in the interval $T \leq t \leq T_2$ for any $T > t_0 + 1$ and any finite $T_2 > T$, provided x is sufficiently large. This may be accomplished by integrating by parts and using the inequalities given above. Thus we find that

$$(2.14) \quad u(t) = \frac{1}{2\pi i} \int_L e^{ts} U(s, t_0) ds \quad (t > t_0 + 1).$$

The formula (2.13) may be used to continue $U(s, t_0)$ analytically into the whole s -plane, cut along the lines of discontinuity of $\exp h(s)$, if we require L_2 to be a contour of the same type as L_1 . Let s' be any characteristic root, let δ' be the residue of $h'(s)$ at s' , and suppose that δ' is not a negative integer. Then by integrating by parts n times and using (2.8) and (2.9), we find from (2.13) that

$$(2.15) \quad \begin{aligned} U(s, t_0) = & \frac{e^{-s} e^{-h(s)}}{s - b_0 - a_0 e^{-s}} \sum_{j=0}^{n-1} (-1)^j G^{(j)}(s, t_0) H_{j+1}(s) \\ & + \frac{(-1)^n e^{-s} e^{-h(s)}}{s - b_0 - a_0 e^{-s}} \int_{s'}^s G^{(n)}(s_1, t_0) H_n(s_1) ds_1 \\ & + J_n e^{-s} (s - s')^{-\delta'-1} \sum_{n=0}^{\infty} h_n (s - s')^n. \end{aligned}$$

This equation is valid in an annulus $0 < |s - s'| \leq C$, or in an annulus cut along a certain line segment, according to the value of δ' . In this formula $H_0(s) = \exp h(s)$ and $H_{n+1}(s)$ is an indefinite integral of $H_n(s)$ for $n = 0, 1, 2, \dots$. Also, each $H_j(s)$ has an expansion

$$(2.16) \quad H_j(s) = (s - s')^{\delta'+j} \sum_{k=0}^{\infty} \frac{d_k (s - s')^k}{(\delta' + k + 1) \cdots (\delta' + k + j)},$$

valid in an appropriate neighborhood of s' . J_n is defined by

$$(2.17) \quad J_n = J_n(s', t_0) = (-1)^n \int_{+\infty+i0}^{s'} G^{(n)}(s_1, t_0) H_n(s_1) ds_1,$$

where the path is of the same type as L_2 . This integral converges if $n + \operatorname{Re}(\delta') > -1$, according to (2.16), as does the integral in (2.15).

A formula similar to (2.15) holds for s near $\bar{s}'$. s' , J_n , δ' , and the h_j must be replaced by their conjugates, and the functions $H_j(s)$ must be replaced by functions $H_j^*(s)$ with expansions

$$H_j^*(s) = (s - \bar{s}')^{\delta'+j} \sum_{k=0}^{\infty} \frac{\bar{d}_k(s - \bar{s}')^k}{(\bar{\delta}' + k + 1) \cdots (\bar{\delta}' + k + j)}$$

near $\bar{s}'$.

We now let $S_2 = X_2 + iY_2$ denote the characteristic root of largest real part at which U has a singularity. We shall define certain functions whose transforms comprise the "principal part" of U at S_2 and $\bar{S}_2$. Let δ_2 be the residue of $h'(s)$ at S_2 . We shall first suppose that δ_2 is not an integer, and shall consider two cases.

Case 1. $\operatorname{Re}(\delta_2) > -1$, δ_2 not an integer. Let any positive integer n be chosen such that $n + \operatorname{Re}(\delta_2) > 1$. Let ν denote the greatest integer less than $\operatorname{Re}(\delta_2)$. Define

$$(2.18) \quad r_j(t) = \frac{t^{\delta_2 - j} e^{S_2 t}}{\Gamma(\delta_2 + 1 - j)} \quad (t \geq 0; j = 0, 1, \dots, \nu + 1),$$

$$(2.19) \quad r_j(t) = \begin{cases} 0 & (0 \leq t < 1) \\ \frac{t^{\delta_2 - j} e^{S_2 t}}{\Gamma(\delta_2 + 1 - j)} & (t \geq 1) \end{cases} \quad (j = \nu + 2, \dots, \nu + n + 2).$$

All the functions $r_j(t)$ are defined as zero for $-1 \leq t < 0$. Define

$$(2.20) \quad r(t) = \sum_{j=0}^{\nu+n+2} h_j r_j(t)$$

and define $R(s)$ to be the transform of $r(t)$. The transform will converge for $\operatorname{Re}(s) > X_2$, and it is well known that

$$(2.21) \quad R(s) = (s - S_2)^{-\delta_2 - 1} \sum_{j=0}^{\nu+n+2} h_j (s - S_2)^j + \text{entire function.}$$

This equation provides a continuation of $R(s)$ into the whole s -plane, cut along certain lines. Also, if $R_c(s)$ denotes the transform of $\bar{r}(t)$, $R_c(s)$ is given by an expression of the form of (2.21), but with S_2 , δ_2 , h_0 , h_1 , $\dots$ replaced by their conjugates. Finally, define

$$(2.22) \quad f(t-1) = f(t-1, t_0) = \begin{cases} 0 & (0 \leq t < 1), \\ -J_n r(t-1) - \bar{J}_n \bar{r}(t-1) & (1 < t < t_0), \\ u(t) - J_n r(t-1) - \bar{J}_n \bar{r}(t-1) & (t_0 \leq t). \end{cases}$$

The Laplace transform of this function exists for sufficiently large x , and is

$$(2.23) \quad F(s) = F(s, t_0) = \int_0^\infty f(t-1)e^{-st}dt$$

$$(2.24) \quad = U(s, t_0) - J_n e^{-s} R(s) - \bar{J}_n e^{-s} R_c(s).$$

(2.24) may be taken as the definition of $F(s, t_0)$ over the whole s -plane, cut along the lines of discontinuity of U .

Case 2. $\text{Re}(\delta_2) \leq -1$, δ_2 not an integer. In this case we define $r_j(t)$ by (2.19) for $j=0, 1, \dots, n$, and take the sums in (2.20) and (2.21) from $j=0$ to $j=n$, but otherwise the discussion is unaltered.

We shall now apply a slightly extended form of a theorem stated in Doetsch [5, p. 269, Satz 4]. We note the following facts:

(a) $F(s, t_0)$ is analytic for $\text{Re}(s) > X_2$ and for $\text{Re}(s) = X_2$, $\text{Im}(s) > Y_2$. As $\text{Re}(s) \rightarrow X_2$ from the right, $F(s, t_0)$ possesses boundary values, denoted by $F(X_2 + iy, t_0)$ or $F(X_2 + iy)$, in the sense that the function $F(s, t_0)$ completed in the half-plane $\text{Re}(s) \geq X_2$ by these values is a continuous function. $F(X_2 + iy)$ is n times differentiable with respect to y , and the n th derivative is continuous for all y . This may be deduced from the expansions (2.15) and (2.21).

(b) The integral

$$\int_{X_2 + i\omega}^{x + i\omega} e^{ts} U(s, t_0) ds \quad (x > X_2; t > t_0)$$

approaches zero as $|\omega| \rightarrow \infty$. This follows from (2.13) and the inequalities (2.10), (2.11), and (2.12).

(c) $U(X_2 + iy)$ and its first $n-1$ derivatives with respect to y approach zero as $|y| \rightarrow \infty$. The proof of this fact is obtained by computing the derivatives of $U(s, t_0)$ and utilizing the following facts.

$$\frac{d^j}{ds^j} e^{h(s)} = e^{h(s)} \phi_j(s),$$

where

$$|\phi_j(X_2 + iy)| \leq \begin{cases} \frac{C}{|X_2 + iy|} & (j = 1, 2, \dots), \\ C & (j = 0), \end{cases}$$

and

$$\frac{d^i}{ds^i} \left(\frac{e^{-h(s)}}{se^s - b_0 e^s - a_0} \right) = e^{-h(s)} \psi_j(s),$$

where

$$|\psi_j(X_2 + iy)| \leq \frac{C}{|X_2 + iy|} \quad (j = 1, 2, \dots).$$

From (a), (b), and (c), we may deduce, as in Doetsch, that

$$(2.25) \quad f(t-1) = \frac{i^n}{2\pi} \frac{e^{X_2 t}}{t^n} \int_{-\infty}^{\infty} e^{ity} \left\{ \frac{d^n}{dy^n} F(X_2 + iy) \right\} dy$$

for $t > t_0 + 1$. Finally, we observe that the integrals

$$\int_{-\infty}^{-\eta} e^{ity} \left\{ \frac{d^n}{dy^n} U(X_2 + iy) \right\} dy \quad \text{and} \quad \int_{\eta}^{\infty} e^{ity} \left\{ \frac{d^n}{dy^n} U(X_2 + iy) \right\} dy,$$

where η is a fixed number greater than Y_2 , are uniformly convergent for $t \geq T$ ($T > 0$). This is readily proved. Consequently, we find, by arguing as in Doetsch, that

$$\lim_{t \rightarrow 0} t^n e^{-X_2 t} [u(t) - J_n r(t-1) - \bar{J}_n \bar{r}(t-1)] = 0.$$

This result is valid for any positive integer n for which $n + \text{Re}(\delta_2) > 1$, provided δ_2 is not an integer. Using the definitions of $r(t)$, we obtain the asymptotic formula (1.8) of Theorem 1.1.

It is still necessary to consider the case in which δ_2 is an integer. If δ_2 is a non-negative integer, we may obtain equation (1.8) by abandoning the above method and using the residue theorem. If δ_2 is a negative integer, equations (2.13) and (2.14) are still valid, but instead of (2.15) we have

$$U(s, t_0) = J e^{-s}(s - S_2)^{-\delta_2-1} \log(s - S_2) \sum_{j=0}^{\infty} h_j (s - S_2)^j + \sum_{j=0}^{\infty} C_j (s - S_2)^j,$$

where J is the residue of $G(s) \exp(h(s))$ at S_2 . By defining

$$r_j(t) = \begin{cases} 0 & (-1 \leq t < 1), \\ (-1)^{q+i}(q-1)! t^{-q} e^{S_2 t} & (t \geq 1) \end{cases}$$

for $j=0, 1, \dots, n+1-q$, where $q = -\delta_2$, and proceeding as before, we again find that equation (1.8) holds. This completes the proof of Theorem 1.1.

3. The nonhomogeneous equation. In this section, we shall consider the equation

$$(3.1) \quad \frac{d}{dt} u(t+1) = \left(a_0 + \frac{a_1}{t} \right) u(t) + \left(b_0 + \frac{b_1}{t} \right) u(t+1) + w(t)$$

where $w(t)$ is a given continuous function, subject to the boundary condition

$$(3.2) \quad u(t) = g(t) \quad (t_0 \leq t \leq t_0 + 1).$$

The principal results relating to equation (3.1) are stated in Theorem 3.1 at the end of this section. They form a necessary preliminary to the discussions in §§4 and 5.

We first observe that there is clearly a unique solution of (3.1) and (3.2). Let us apply the Laplace transform formally to (3.1), as in §2 of this paper, solve the resulting differential equation, and employ the customary inversion. The function

$$(3.3) \quad u(t) = u_0(t) + u_1(t)$$

is thus suggested as a possible solution of (3.1), where $u_0(t)$ is the solution of the homogeneous equation discussed in the preceding section and where

$$(3.4) \quad u_1(t) = -\frac{1}{2\pi i} \int_L \frac{e^{ts} e^{-h(s)}}{se^s - b_0 e^s - a_0} \cdot \left\{ \int_{+\infty+i0, L_2}^s e^{h(s_1)} \left(\int_{t_0}^{\infty} t_1 w(t_1) e^{-s_1 t_1} dt_1 \right) ds_1 \right\} ds.$$

Before showing that (3.3) actually gives the desired solution, we observe that, if $w(t)$ is continuous for $t > t_0$ and if

$$\int_{t_0}^{\infty} t_1 w(t_1) e^{-s t_1} dt_1$$

is absolutely convergent for $\operatorname{Re}(s) > X_1$, the integrals

$$\int_{+\infty+i0}^s e^{h(s_1)} \left(\int_{t_0}^{\infty} t_1 w(t_1) e^{-s_1 t_1} dt_1 \right) ds_1,$$

and

$$\int_{t_0}^{\infty} t_1 w(t_1) \left(\int_{+\infty+i0}^s e^{h(s_1)} e^{-s_1 t_1} ds_1 \right) dt_1$$

exist for $x = \operatorname{Re}(s) > X_1$, and are equal. This follows from standard theorems on interchange of order. Moreover,

$$\int_{-\infty}^{\infty} \frac{e^{i\tau y}}{x + iy - b_0 - a_0 e^{-x-iy}} dy$$

is uniformly convergent in every finite interval $\tau_1 \leq \tau \leq \tau_2$, where $\tau_1 > 0$ [$\tau_2 < 0$], and boundedly convergent for $\tau > 0$ [$\tau < 0$], provided $x > X_1$. We can also show that

$$(3.5) \quad \int_L \frac{e^{ts}e^{-h(s)}}{s - b_0 - a_0e^{-s}} \left(\int_{+\infty+i0}^s e^{h(s_1)}e^{-s_1t_1}ds_1 \right) ds = 0,$$

if $t_1 > t \geq t_0 - 1$, by integrating the inner integral by parts and shifting the contour L arbitrarily far to the right. It therefore follows from standard theorems that

$$\begin{aligned} & -2\pi i u_1(t+1) \\ &= \int_L \frac{e^{ts}e^{-h(s)}}{s - b_0 - a_0e^{-s}} \left\{ \int_{t_0}^{\infty} t_1 w(t_1) \left(\int_{L_2} e^{h(s_1)}e^{-s_1t_1}ds_1 \right) dt_1 \right\} ds \\ &= \int_L \frac{e^{ts}e^{-h(s)}}{s - b_0 - a_0e^{-s}} \left\{ \int_{L_2} e^{h(s_1)} \left(\int_{t_0}^{\infty} t_1 w(t_1) e^{-s_1t_1} dt_1 \right) ds_1 \right\} ds \\ (3.6) \quad &= \int_{t_0}^{\infty} t_1 w(t_1) \left\{ \int_L \frac{e^{ts}e^{-h(s)}}{s - b_0 - a_0e^{-s}} \left(\int_{L_2} e^{h(s_1)}e^{-s_1t_1}ds_1 \right) ds \right\} dt_1 \\ &= \int_{t_0}^t t_1 w(t_1) \left\{ \int_L \frac{e^{ts}e^{-h(s)}}{s - b_0 - a_0e^{-s}} \left(\int_{L_2} e^{h(s_1)}e^{-s_1t_1}ds_1 \right) ds \right\} dt_1, \end{aligned}$$

where each integral exists for $t > t_0$ and $x > X_1$. The path L is the straight line from $x - i\infty$ to $x + i\infty$.

We shall now prove that the function $u(t)$ defined by (3.3) is the unique solution of (3.1) and (3.2). In order to prove that $u(t)$ satisfies the boundary condition, we must demonstrate that $u_1(t) = 0$ for $t_0 \leq t \leq t_0 + 1$. This follows, for $t_0 \leq t < t_0 + 1$, from the third equation of (3.6) by shifting L to the right. $u_1(t_0 + 1)$ may be defined to be zero.

It must still be proved that $u(t+1)$ is a solution of (3.1) for $t > t_0$. Since $u_0(t)$ is a solution of the homogeneous equation discussed in §2, it will be enough to show that $u_1(t)$ is a particular solution of (3.1). It seems to be difficult to do this directly. Instead, we adopt the following device. Let

$$\begin{aligned} I_1(t) &= u_1(t+1) - a_0 \int_{t_0}^t u_1(t_1) dt_1 - a_1 \int_{t_0}^t \frac{u_1(t_1)}{t_1} dt_1 \\ (3.7) \quad &- b_0 \int_{t_0}^t u_1(t_1+1) dt_1 - b_1 \int_{t_0}^t \frac{u_1(t_1+1)}{t_1} dt_1 - \int_{t_0}^t w(t_1) dt_1. \end{aligned}$$

We shall now show that $I_1(t)$ is identically zero for $t > t_0$. The required result will then follow by differentiation. For convenience, define

$$(3.8) \quad k(t, t_1) = -\frac{t_1}{2\pi i} \int_L \frac{e^{ts}e^{-h(s)}}{s - b_0 - a_0e^{-s}} \left(\int_{L_2} e^{h(s_1)}e^{-s_1t_1}ds_1 \right) ds$$

for t and t_1 greater than $t_0 - 1$. As shown above, $k(t, t_1)$ is independent of x as long as $x > X_1$, and $k(t, t_1) = 0$ for $t_1 > t \geq t_0 - 1$. By bounded convergence of the

integral, $k(t, t_1)$ is a continuous function of t and t_1 as long as $t > t_1 \geq t_0 - 1$, and therefore $u_1(t)$ is continuous. From (3.6),

$$(3.9) \quad u_1(t+1) = \int_{t_0}^t w(t_1) k(t, t_1) dt_1.$$

Now if $q(t_1, t_2)$ is any function that is continuous in t_1 and t_2 for $t \geq t_1 > t_2 \geq t_0$, it is easy to see that

$$(3.10) \quad \int_{t_0}^t dt_1 \int_{t_0}^{t_1} q(t_1, t_2) dt_2 = \int_{t_0}^t dt_2 \int_{t_2}^t q(t_1, t_2) dt_1.$$

By using this equation and (3.9) we can show that

$$\begin{aligned} \int_{t_0}^t u_1(t_1) dt_1 = & -\frac{1}{2\pi i} \int_L \frac{e^{(t-1)s} e^{-h(s)}}{s(s-b_0-a_0 e^{-s})} \\ & \cdot \left\{ \int_{L_2} e^{h(s_1)} \left(\int_{t_0}^{\infty} t_2 w(t_2) e^{-s_1 t_2} dt_2 \right) ds_1 \right\} ds. \end{aligned}$$

Formulas for the other integrals appearing in (3.7) may be deduced directly from (3.4). Combining these results yields the equation

$$\begin{aligned} 2\pi i I_1(t) = & - \int_L \frac{e^{ts} e^{-h(s)}}{s} \left\{ \int_{L_2} e^{h(s_1)} \left(\int_{t_0}^{\infty} t_2 w(t_2) e^{-s_1 t_2} dt_2 \right) ds_1 \right\} ds \\ & + \int_{t_0}^t \frac{dt_1}{t_1} \int_L e^{t_1 s} h'(s) e^{-h(s)} \\ & \cdot \left\{ \int_{L_2} e^{h(s_1)} \left(\int_t^{\infty} t_2 w(t_2) e^{-s_1 t_2} dt_2 \right) ds_1 \right\} ds \\ & - 2\pi i \int_{t_0}^t w(t_1) dt_1 \quad (t \geq t_0). \end{aligned} \quad (3.11)$$

We now integrate the integral over L_2 by parts, use Doetsch [5, p. 107, Theorem 5], and change the order of integration, obtaining

$$\begin{aligned} 2\pi i I_1 = & - \int_{t_0}^t w(t_2) dt_2 \int_L \frac{e^{ts} e^{-h(s)}}{s} \left(\int_{L_2} e^{h(s_1)} h'(s_1) e^{-s_1 t_2} ds_1 \right) ds \\ & + \int_{t_0}^t \frac{dt_1}{t_1} \int_{t_0}^{t_1} t_2 w(t_2) dt_2 \int_L e^{t_1 s} h'(s) e^{-h(s)} \\ & \cdot \left(\int_{L_2} e^{h(s_1)} e^{-s_1 t_2} ds_1 \right) ds. \end{aligned} \quad (3.12)$$

We now let $I_2(t_1, t_2)$ denote the integral over L appearing in the second term above. Using integration by parts, we find that

$$I_2 = -\frac{1}{t_2} \int_L e^{t_1 s} \left\{ \frac{d}{ds} \left(e^{-h(s)} \int_{L_2} e^{h(s_1)} h'(s_1) e^{-s_1 t_2} ds_1 \right) \right\} ds$$

$$= \frac{t_1}{t_2} \int_L e^{t_1 s} e^{-h(s)} \left(\int_{L_2} e^{h(s_1)} e^{-s_1 t_2} ds_1 \right) ds.$$

By using this result in the second term of (3.12), then using (3.10), and finally interchanging the order of integration, we find that $I_1(t) = 0$ for $t > t_0$, as we set out to prove. Therefore $u(t)$ is the solution of (3.1) and (3.2).

The results of this section are summarized in the theorem below.

THEOREM 3.1. *If $w(t)$ is continuous for $t > t_0$ and if*

$$\int_{t_0}^{\infty} t_1 w(t_1) e^{-s t_1} dt_1$$

is absolutely convergent for $\operatorname{Re}(s) > X_1$, the unique function which satisfies (3.1) for $t > t_0$ and which satisfies (3.2) for $t_0 \leq t \leq t_0 + 1$ is

$$u(t) = u_0(t) + u_1(t).$$

Here $u_0(t)$ is the function discussed in §2, and for $t > t_0$

$$u_1(t+1) = \int_{t_0}^t w(t_1) k(t, t_1) dt_1,$$

where $k(t, t_1)$ is defined by (3.8).

4. The general linear equation. We now come to the proof of the principal results of this article as stated in Theorems 1.2 and 1.3. We shall construct a function $u(t)$ which, for $t > t_0$, satisfies the equation

$$(4.1) \quad \frac{d}{dt} u(t+1) = a(t)u(t) + b(t)u(t+1),$$

where $a(t)$ and $b(t)$ have asymptotic expansions

$$(4.2) \quad a(t) \sim a_0 + \frac{a_1}{t} + \frac{a_2}{t^2} + \dots, \quad b(t) \sim b_0 + \frac{b_1}{t} + \frac{b_2}{t^2} + \dots,$$

as $t \rightarrow +\infty$, and which satisfies the condition

$$(4.3) \quad u(t) = g(t)$$

for $t_0 \leq t \leq t_0 + 1$. It is clear that such a function exists, and is unique. Since equation (4.1) may be written in the form of equation (3.1), where $w(t) = A(t)u(t) + B(t)u(t+1)$ and

$$(4.4) \quad A(t) \sim \frac{a_2}{t^2} + \frac{a_3}{t^3} + \dots, \quad B(t) \sim \frac{b_2}{t^2} + \frac{b_3}{t^3} + \dots,$$

the results of the preceding section suggest the consideration of the integral equation

$$(4.5) \quad u(t+1) = u_0(t+1) + \int_{t_0}^t \{A(t_1)u(t_1) + B(t_1)u(t_1+1)\} k(t, t_1) dt_1.$$

$u_0(t)$ and $k(t, t_1)$ are defined above.

We shall construct the unique solution of (4.5) by the method of successive approximations, and deduce Theorem 1.2 from the results. Before we can do this, however, we must obtain some further information concerning $k(t, t_1)$. This will be done by a method similar to that employed in §2. First we observe that the Laplace transform

$$(4.6) \quad K(s, t_1) = \int_0^\infty k(t, t_1) e^{-st} dt = \int_{t_1}^\infty k(t, t_1) e^{-st} dt$$

exists for $\text{Re}(s) > X_1$, and by (3.8) and an extended form of Cauchy's Integral Formula,

$$(4.7) \quad K(s, t_1) = - \frac{t_1 e^{-h(s)}}{s - b_0 - a_0 e^{-s}} \int_{+\infty+i0, L_2}^s e^{h(s_1)} e^{-s_1 t_1} ds_1.$$

(4.7) provides an analytic continuation of $K(s, t_1)$ into the whole s -plane, cut along various lines. Let s' be any characteristic root, let δ' be the residue of $h'(s)$ at s' , and define

$$(4.8) \quad J_n(t_1) = J_n(s', t_1) = t_1^n \int_{+\infty+i0}^{s'} H_n(s_1) e^{-s_1 t_1} ds_1.$$

Exactly as in §2, we find that for any s in a certain annulus $0 < |s - s'| \leq C$, cut along the line of discontinuity of K , if any,

$$(4.9) \quad \begin{aligned} - \frac{K(s, t_1)}{t_1} &= \frac{e^{-h(s)} e^{-s t_1}}{s - b_0 - a_0 e^{-s}} \sum_{j=1}^n H_j(s) t_1^{j-1} \\ &+ \frac{t_1^n e^{-h(s)}}{s - b_0 - a_0 e^{-s}} \int_{s'}^s H_n(s_1) e^{-s_1 t_1} ds_1 \\ &+ J_n(t_1) (s - s')^{-\delta'-1} \sum_{j=0}^\infty h_j (s - s')^j, \end{aligned}$$

provided δ' is not a negative integer. In the cut annulus $0 < |s - s'| \leq C$, a similar formula is valid; the $H_n(s)$ must be replaced by related functions and s' , J_n , δ' , and the h_j must be replaced by their conjugates. The path of integration in (4.9) is the line joining s' and s .

As in §2, the cases in which δ' is an integer will be treated separately later.

Let S_1 be the characteristic root of largest real part, and let δ_1 be the

residue of $h'(s)$ at S_1 . We shall show later that $K(s, t_1)$ has a singularity at S_1 for every value of t_1 , save possibly for a sequence of values of t_1 with sole limit point at infinity. Moreover, whether the singularity is a pole or a branch point depends only on δ_1 . For the time being, we assume this to be so. We remark that the possibility of the exceptional values of t_1 is of no importance in characterizing $k(t, t_1)$, since we have noted previously that k is a continuous function.

We now define auxiliary functions as in §2.

Case 1. $\text{Re}(\delta_1) > -1$, δ_1 not an integer. Let any positive integer n be chosen such that $n + \text{Re}(\delta_1) > 1$, and let ν be the integer such that $\text{Re}(\delta_1) - 1 \leq \nu < \text{Re}(\delta_1)$. Define functions $r_j(t, S_1)$ ($j=0, 1, \dots, \nu+n+2$) as in equations (2.18) and (2.19), but with S_2 replaced by S_1 and δ_2 by δ_1 . Define $r(t, S_1)$ by an equation analogous to (2.20), and let $R(s, S_1)$ be the transform of $r(t, S_1)$, and $R_c(s, S_1)$ the transform of $\bar{r}(t, S_1)$. We obtain an analogue of equation (2.21). Finally, define

$$(4.10) \quad f(t, t_1) = \begin{cases} -J_n(t_1)r(t, S_1) - \bar{J}_n(t_1)\bar{r}(t, S_1) & (0 \leq t < t_0) \\ -\frac{k(t, t_1)}{t_1} - J_n(t_1)r(t, S_1) - \bar{J}_n(t_1)\bar{r}(t, S_1) & (t_1 \geq t_0, t \geq t_0) \end{cases}$$

and define $F(s, t_1)$ to be the transform of $f(t, t_1)$. We see that for $t_1 \geq t_0$

$$(4.11) \quad F(s, t_1) = -\frac{K(s, t_1)}{t_1} - J_n(t_1)R(s, S_1) - \bar{J}_n(t_1)R_c(s, S_1).$$

Case 2. $\text{Re}(\delta_1) \leq -1$, δ_1 not an integer. Our procedure is similar, and we omit the details.

The procedure of §2 yields, in place of equation (2.25),

$$(4.12) \quad f(t, t_1) = \frac{i^n}{2\pi} \frac{e^{X_1 t}}{t^n} \int_{-\infty}^{\infty} e^{i t y} \left\{ \frac{d^n}{dy^n} F(X_1 + iy, t_1) \right\} dy,$$

where the boundary values of $F(s, t_1)$ are denoted by $F(X_1 + iy, t_1)$. This formula holds for all $t_1 > t_0$.

At this point, we must alter the procedure of §2. Our next step is to prove the following lemma.

LEMMA 4.1. *If δ_1 is not an integer, if n is any positive integer for which $n + \text{Re}(\delta_1) > 1$, and if $t_1 > t_0$, there are positive numbers C and C_1 , which do not depend on t_1 or t , such that $|J_n(S_1, t_1)| \leq C t_1^{-\text{Re}(\delta_1) - C_1} e^{-X_1 t_1}$.*

$J_n(S_1, t_1)$ is defined by (4.8) above. We suppose first that $\text{Re}(\delta_1) \leq 0$. If N is the positive integer such that $N < n + \text{Re}(\delta_1) \leq N+1$, integration by parts yields

$$J_n(S_1, t_1) = t_1^{n-N-1} \int_{+\infty+i0}^{S_1} H_{n-N-1}(s_1) e^{-s_1 t_1} ds_1.$$

Clearly the path may be deformed into the line from $+\infty + iY_1$ to S_1 . If $\text{Re}(\delta_1)$ is not an integer, $|H_{n-N-1}(x_1 + iY_1)| \leq C|x_1 + iY_1|^c$, as may be deduced from (2.10) and the definition of $H_j(s)$, and the result follows at once. If $\text{Re}(\delta_1)$ is an integer, (2.16) implies that $|H_{n-N-1}(x_1 + iY_1)| \leq C$ for x_1 near X_1 . If we split the integral into two parts, in one of which this bound may be employed, the stated result follows easily.

If $\text{Re}(\delta_1) > 0$, we have, instead,

$$J_n(S_1, t_1) = t_1^{-(N-n+1)} \int_{+\infty+i0}^{S_1} \frac{d^{N-n+1}}{ds_1^{N-n+1}} \{e^{h(s_1)}\} e^{-s_1 t_1} ds_1,$$

since the first $N-n$ derivatives of $\exp\{h(s)\}$ approach zero as s approaches S_1 . We can now complete the proof just as before.

We shall also need the following result: If $\eta_2 > Y_1 \geq 0$, there is a constant C , depending on η_2 but not on τ , such that

$$(4.13) \quad \left| \int_{-\infty}^{-\eta_2} \frac{e^{i\tau y}}{X_1 + iy - b_0 - a_0 e^{-X_1 - iy}} dy + \int_{\eta_2}^{\infty} \frac{e^{i\tau y}}{X_1 + iy - b_0 - a_0 e^{-X_1 - iy}} dy \right| \leq C$$

for any $\tau > 0$, or for any $\tau < 0$. To prove this, it is clearly enough to consider

$$I_3(\tau) = \int_{-\infty}^{-\eta_2} \frac{e^{i\tau y}}{y} dy + \int_{\eta_2}^{\infty} \frac{e^{i\tau y}}{y} dy.$$

By integration by parts, we see that each of these integrals is uniformly convergent if τ is bounded away from zero, and approaches zero as $\tau \rightarrow \infty$. It will therefore suffice to show that $I_3(\tau)$ is bounded as $\tau \rightarrow +0$ and as $\tau \rightarrow -0$. Suppose that $\tau > 0$, and consider the integral of e^z/z over the contour in the z -plane which follows the imaginary axis from $-Ri$ to $+Ri$, except for an indentation on the semicircle $|z| = \tau\eta_2$, $\text{Re}(z) \leq 0$, then follows the horizontal straight segment from Ri to $-\sigma + Ri$, then the vertical segment to $-\sigma - Ri$, and finally the horizontal segment back to $-Ri$. Since the value of this integral is zero, the stated result follows upon letting $R \rightarrow +\infty$ and then letting $\sigma \rightarrow +\infty$.

We shall now obtain a bound on $|f(t, t_1)|$, using (4.12). Define

$$I_4(\alpha, \beta) = \int_{\alpha}^{\beta} e^{i\tau y} \left\{ \frac{d^n}{dy^n} F(X_1 + iy, t_1) \right\} dy.$$

First we shall show that, given $\epsilon > 0$, we may choose $\eta_1 = \eta_1(\epsilon)$ and $\eta_2 = \eta_2(\epsilon)$,

with $0 < \eta_1 < Y_1 < \eta_2$, such that $|I_4(\eta_1, \eta_2)| < \epsilon t_1^n e^{-X_1 t_1}$ and $|I_4(-\eta_2, -\eta_1)| < \epsilon t_1^n e^{-X_1 t_1}$ for all $t > t_1 \geq t_0$. It will be enough to consider $I_4(\eta_1, \eta_2)$, and to restrict ourselves to the case in which $\operatorname{Re}(\delta_1) > -1$ and δ_1 is not an integer. What we must prove is that for y in some fixed interval about Y_1 ,

$$(4.14) \quad \left| \frac{d^n}{dy^n} F(X_1 + iy, t_1) \right| \leq C t_1^n e^{-X_1 t_1},$$

where C does not depend on t_0, t, t_1 , or y . By (4.9) and (4.11),

(4.15) $F(s, t_1) = V_n(s, t_1) + Q_n(s, t_1) - \bar{J}_n(t_1) R_c(s, S_1) - J_n(t_1)$ entire function in the vicinity of S_1 , where

$$V_n(s, t_1) = \frac{e^{-h(s)}}{s - b_0 - a_0 e^{-s}} \left[e^{-s t_1} \sum_{j=1}^n H_j(s) t_1^{j-1} + t_1^n \int_{S_1}^s H_n(s_1) e^{-s_1 t_1} ds_1 \right],$$

and

$$Q_n(s, t_1) = J_n(t_1) (s - S_1)^{-\delta_1 - 1} \sum_{j=\nu+n+3}^{\infty} h_j(s - S_1)^j.$$

Since $n + \operatorname{Re}(\delta_1) > 1$, and since $R_c(s, S_1)$ is analytic near S_1 , Lemma 4.1 shows that the contribution of the last two terms in (4.15) satisfies (4.14). The term arising from Q is bounded as required by choice of ν . Finally, V_n may be handled by a calculation using the series representations (2.8), (2.9), and (2.16).

Next we shall prove that $|I_4(-\eta_1, \eta_1)| \leq C t_1^{n-1} e^{-X_1 t_1}$ if $0 < \eta_1 < Y_1$, where C depends on η_1 but not on t, t_1 , or t_0 . It will be enough to show that the derivative in the integrand is so bounded for $|y| \leq \eta_1$. Since the boundary functions of K, R , and R_c exist separately over this range, we see from Lemma 4.1 that we need only consider the n th derivative of $-K(X_1 + iy, t_1)/t_1$. From equation (4.7) we obtain

$$(4.16) \quad \frac{d^n}{ds^n} \left\{ -\frac{K(s, t_1)}{t_1} \right\} = \frac{d^n}{ds^n} \left(\frac{e^{-h}}{\zeta} \right) \int_{L_2} e^{h(s_1)} e^{-s_1 t_1} ds_1 \\ + e^{-s t_1} \sum_{\mu=1}^n \binom{n}{\mu} \frac{d^{n-\mu}}{ds^{n-\mu}} \left(\frac{e^{-h}}{\zeta} \right) \sum_{\nu=0}^{\mu-1} (-t_1)^\nu \binom{\mu-1}{\nu} \frac{d^{\mu-1-\nu}}{ds^{\mu-1-\nu}} (e^h)$$

where $\zeta(s) = s - b_0 - a_0 e^{-s}$. Since all the functions of s in (4.16) are bounded for $s = X_1 + iy$, $|y| \leq \eta_1$, the desired result is clear.

Finally we shall prove that if $\eta_2 > Y_1 \geq 0$, there is a constant C , depending on η_2 but not on t, t_1 ; or t_0 , such that

$$(4.17) \quad |I_4(-\infty, -\eta_2) + I_4(\eta_2, \infty)| \leq C t_1^{n-1} e^{-X_1 t_1}$$

for $t > t_1 \geq t_0$. To do this, we first consider

$$I_5 = \int_{-\infty}^{-\eta_2} e^{ity} \left\{ \frac{d^n}{dy^n} \frac{K(X_1 + iy, t_1)}{-t_1} \right\} dy + \int_{\eta_2}^{\infty} e^{ity} \left\{ \frac{d^n}{dy^n} \frac{K(X_1 + iy, t_1)}{-t_1} \right\} dy.$$

The n th derivative of $K(s, t_1)/t_1$ is given by equation (4.16). The portion of I_5 due to the term for which $\mu = n$, $\nu = n - 1$, has the desired bound by virtue of (4.13). For the other terms, we proceed in a manner analogous to that used in §2 to prove that $U(X_2 + iy)$ and its first $n - 1$ derivatives approach zero as $|y| \rightarrow \infty$. The proof of (4.17) may then be completed with the aid of Lemma 4.1.

By combining the above results, we find that, given $\epsilon > 0$,

$$|I_4(-\infty, \infty)| \leq C(\epsilon) t_1^{n-1} e^{-X_1 t_1} + \epsilon t_1^n e^{-X_1 t_1}, \quad \text{for } t > t_1 \geq t_0,$$

where $C(\epsilon)$ does not depend on t_0 , t , or t_1 . This inequality, in combination with (4.12), provides a useful bound on $f(t, t_1)$. By proceeding somewhat as in §2, we can obtain a similar result in case δ_1 is an integer. We omit the details. The final conclusions are summarized in the theorem which follows.

THEOREM 4.1. *Let S_1 be the characteristic root of largest real part and let $\delta = \delta_1$ be the residue of $h'(s)$ at S_1 .*

(1) *If δ is a non-negative integer,*

$$(4.18) \quad -\frac{k(t, t_1)}{t_1} = J(t_1)r(t, S_1) + f(t, t_1)$$

where

$$(4.19) \quad J(t_1) = \int_{+\infty+i0}^{S_1} e^{h(s_1)} e^{-s_1 t_1} ds_1,$$

$$(4.20) \quad r(t, S_1) = t^\delta e^{S_1 t} \left(C_0 + \frac{C_1}{t} + \cdots + \frac{C_\delta}{t^\delta} \right),$$

$$(4.21) \quad |f(t, t_1)| \leq C e^{\alpha(t-t_1)} \quad (x < X_1).$$

(2) *If δ is a negative integer,*

$$(4.22) \quad -\frac{k(t, t_1)}{t_1} = J(t_1)r(t, S_1) + \bar{J}(t_1)\bar{r}(t, S_1) + f(t, t_1)$$

where

$$(4.23) \quad r(t, S_1) = t^\delta e^{S_1 t} \left(C_0 + \frac{C_1}{t} + \cdots + \frac{C_{\delta+n-1}}{t^{\delta+n-1}} \right),$$

and where

$$(4.24) \quad J(t_1) = \frac{1}{2\pi i} \int e^{h(s)} e^{-s t_1} ds = t^{-\delta-1} e^{-S_1 t_1} \left(C_0 + \dots + \frac{C_{-\delta-1}}{t_1^{-\delta-1}} \right),$$

the integral being taken around a small circle surrounding S_1 . Also, given $\epsilon > 0$, there exists $C(\epsilon)$ such that

$$(4.25) \quad |f(t, t_1)| \leq \frac{t_1^{n-1}}{t^n} e^{X_1(t-t_1)} [C(\epsilon) + \epsilon t_1]$$

for $t_1 > t \geq t_0$ and any positive integer n for which $n + \operatorname{Re}(\delta_1) > 1$.

(3) If δ is not an integer, the results are as in (2), except that $J(t_1) = J_n(S_1, t_1)$ is defined by (4.8) and

$$(4.26) \quad r(t, S_1) = \begin{cases} t^\delta e^{S_1 t} \left(C_0 + \frac{C_1}{t} + \dots + \frac{C_{r+n+2}}{t^{r+n+2}} \right) & \text{if } \operatorname{Re}(\delta) > -1, \\ t^\delta e^{S_1 t} \left(C_0 + \frac{C_1}{t} + \dots + \frac{C_n}{t^n} \right) & \text{if } \operatorname{Re}(\delta) \leq -1. \end{cases}$$

The above theorem was derived under the assumption that $K(s, t_1)$ has a singularity at S_1 for every value of t_1 , save possibly for a sequence of values of t_1 with sole limit point at infinity. We shall now prove that this is true. We first observe from the above discussion that a necessary and sufficient condition in order that $K(s, t_1)$ should have a singularity at S_1 and $\bar{S}_1$, for a fixed t_1 , is that $J(t_1) \neq 0$. Let us now consider the function

$$I_\delta(S_1, t_1) = \int_{+\infty+i0}^{S_1} H_n(\sigma) e^{-\sigma t_1} d\sigma,$$

which, for the moment, we regard as a function of the complex variable t_1 . Since the integral is uniformly convergent for $\operatorname{Re}(t_1)$ bounded away from zero, I_δ is an analytic function of t_1 for $\operatorname{Re}(t_1) > 0$. Consequently I_δ , as a function of the real variable t_1 , can be zero only for a sequence of values of $t_1 > 0$ with sole limit point at infinity, unless it is identically zero. If δ_1 is an integer, the same argument may be applied to the corresponding integral in the definition of J . Thus in order to complete the proof we need only show that the appropriate integral cannot be zero for all $t_1 > 0$. Let us suppose that δ_1 is not an integer and that $I_\delta(S_1, t_1) = 0$ for all $t_1 > 0$. Then, regarding t_1 as a complex variable,

$$-e^{iY_1 t_1} I_\delta = \int_x^\infty H_n(x + iY_1) e^{-x t_1} dx$$

is zero for $\operatorname{Re}(t_1) > 0$. Let

$$\Phi(t_1) = \int_0^\infty \phi(x) e^{-xt_1} dx$$

where

$$\phi(x) = \begin{cases} \operatorname{Re} \{H_n(x + iY_i)\} & \text{if } x > X_1, \\ 0 & \text{if } 0 < x < X_1. \end{cases}$$

If I_6 is identically zero, then $\Phi(t_1)$ is zero for $\operatorname{Re}(t_1) > 0$. But $\Phi(t_1)$ is the transform of $\phi(x)$. It follows from Doetsch [5, p. 135, Theorem 2], that $\phi(x)$ is identically zero. This is a contradiction. Hence I_6 is not identically zero. A similar argument may be used if δ_1 is an integer. The proof of Theorem 4.1 is therefore complete.

We can now prove Theorem 1.2. We shall construct a solution of the integral equation (4.5), using the classical method of successive approximations. Define

$$\begin{aligned} u_{m+1}(t) &= u_0(t) = g(t) & (t_0 \leq t \leq t_0 + 1; m = 0, 1, 2, \dots), \\ (4.27) \quad u_{m+1}(t+1) &= u_0(t+1) \\ &+ \int_{t_0}^t \{A(t_1)u_m(t_1) + B(t_1)u_m(t_1+1)\} k(t, t_1) dt_1 \\ & & (t > t_0; m = 0, 1, 2, \dots). \end{aligned}$$

$u_0(t)$ is the solution of the equation of first approximation. Note that the boundary condition (4.3) is satisfied by each iterate.

According to the results of §2,

$$(4.28) \quad |u_0(t+1)| \leq Ct^{\operatorname{Re}(\delta_2)} e^{X_2 t} \leq \alpha_1 t^{\operatorname{Re}(\delta_1)} e^{X_1 t}$$

for $t \geq t_0 - 1$. We shall now prove by induction that for $t > t_0$

$$(4.29) \quad |u_m(t+1)| \leq 5\alpha_1 t^{\operatorname{Re}(\delta_1)} e^{X_1 t},$$

from which it will follow, since $u_m(t) = u_0(t)$ for $t_0 \leq t \leq t_0 + 1$, that there is a constant α_2 such that

$$(4.30) \quad |u_m(t)| \leq 5\alpha_1 \alpha_2 t^{\operatorname{Re}(\delta_1)} e^{X_1 t}$$

for $t \geq t_0$. As just observed, (4.29) is true for $m=0$, and hence so is (4.30). We suppose that they have been proved for $m=0, 1, \dots, p$, and attempt to prove (4.29) for $m=p+1$. By substituting for $k(t, t_1)$ in (4.27), using (4.18) or (4.22), and by observing from (4.4) that

$$(4.31) \quad |A(t)| \leq \frac{A}{t^2}, \quad |B(t)| \leq \frac{B}{t^2},$$

we obtain

$$\begin{aligned}
|u_{p+1}(t+1)| &\leq |u_0(t+1)| + 2A |r(t, S_1)| \int_{t_0}^t t_1^{-1} |J(t_1)| |u_p(t_1)| dt_1 \\
&\quad + 2B |r(t, S_1)| \int_{t_0}^t t_1^{-1} |J(t_1)| |u_p(t_1+1)| dt_1 \\
(4.32) \quad &\quad + A \int_{t_0}^t t_1^{-1} |f(t, t_1)| |u_p(t_1)| dt_1 \\
&\quad + B \int_{t_0}^t t_1^{-1} |f(t, t_1)| |u_p(t_1+1)| dt_1.
\end{aligned}$$

Each term in (4.32) may be shown to be bounded by $\alpha_1 t^{\text{Re}(\delta_1)} e^{X_1 t}$ by using the following inequalities:

$$(4.33) \quad |r(t, S_1)| \leq C t^{\text{Re}(\delta_1)} e^{X_1 t} \quad (t > 1),$$

$$(4.34) \quad |J(t_1)| \leq C t_1^{-C - \text{Re}(\delta_1)} e^{-X_1 t_1} \quad (t_1 > t_0).$$

The first comes from Theorem 4.1 and the second from Lemma 4.1 and Theorem 4.1. In treating the last two integrals in (4.32) when δ_1 is not an integer, or when δ_1 is a negative integer, we use the bound (4.25), with $\epsilon = 1/10A\alpha_2$, and the fact that $n + \text{Re}(\delta_1) > 1$. Thus (4.29) and (4.30) are proved.

The successive approximations defined by (4.27) obviously converge to $g(t)$ for $t_0 \leq t \leq t_0 + 1$. We shall now prove that they converge for $t > t_0 + 1$ by proving that the series

$$(4.35) \quad \sum_{m=0}^{\infty} \{u_{m+1}(t+1) - u_m(t+1)\}$$

converges for $t > t_0$. We can prove by induction, in much the same way (4.29) was established, that

$$(4.36) \quad |u_{m+1}(t+1) - u_m(t+1)| t^{-\text{Re}(\delta_1)} e^{-X_1 t} \leq 10 \frac{\alpha_3^m (t - t_0)^m}{m!}$$

for $t > t_0$, $m = 0, 1, 2, \dots$. α_3 is a constant which does not depend on m . (4.36) shows immediately that (4.35) is uniformly convergent in any finite interval in which $t > t_0$. Thus the sequence $u_0(t+1), u_1(t+1), \dots$, of approximations converges uniformly in every finite interval to a certain function $u(t+1)$.

It is clear that $u(t+1)$ is continuous for $t > t_0$, and, by (4.30), that

$$(4.37) \quad |u(t)| \leq C t^{\text{Re}(\delta_1)} e^{X_1 t}.$$

By reason of the definitions (4.27) and the uniformity of convergence, $u(t)$ satisfies the boundary condition (4.3) and for $t > t_0$ it satisfies the integral equation (4.5). Finally, because of (4.37), the integral

$$\int_{t_0}^{\infty} t_1 \{A(t_1)u(t_1) + B(t_1)u(t_1 + 1)\} e^{-s t_1} dt_1$$

is absolutely convergent for $\operatorname{Re}(s) > X_1$. We can therefore prove that $u(t)$ satisfies the differential-difference equation (4.1) for $t > t_0$ by retracing the discussion in §3. This completes the proof of Theorem 1.2.

5. The nonlinear equation. We shall now discuss the nonlinear equation

$$(5.1) \quad \frac{d}{dt} u(t+1) = a(t)u(t) + b(t)u(t+1) + D(u(t), u(t+1)),$$

under the conditions stated in Theorem 1.3. We wish to examine the behavior, as $t \rightarrow +\infty$, of a function $u(t)$ which satisfies (5.1) for $t > t_0$ and which satisfies

$$(5.2) \quad u(t) = g(t)$$

for $t_0 \leq t \leq t_0 + 1$. Since (5.1) may be written in the form of equation (3.1), with $w(t) = A(t)u(t) + B(t)u(t+1) + D(u(t), u(t+1))$ and

$$(5.3) \quad A(t) \sim \frac{a_2}{t^2} + \frac{a_3}{t^3} + \cdots, \quad B(t) \sim \frac{b_2}{t^2} + \frac{b_3}{t^3} + \cdots,$$

as $t \rightarrow +\infty$, the results of §3 suggest the consideration of the integral equation

$$(5.4) \quad u(t+1) = u_0(t+1) + \int_{t_0}^t \{A(t_1)u(t_1) + B(t_1)u(t_1+1) + D(u(t_1), u(t_1+1))\} k(t, t_1) dt_1.$$

We shall now construct a solution of (5.4) by the method of successive approximations. Define

$$(5.5) \quad \begin{aligned} u_{m+1}(t) &= u_0(t) = g(t) & (t_0 \leq t \leq t_0 + 1; m = 0, 1, 2, \dots), \\ u_{m+1}(t+1) &= u_0(t+1) + \int_{t_0}^t \{A(t_1)u_m(t_1) + B(t_1)u_m(t_1+1) \\ &\quad + D(u_m(t_1), u_m(t_1+1))\} k(t, t_1) dt_1 \\ &\quad (t > t_0; m = 0, 1, 2, \dots). \end{aligned}$$

As in §4, our first aim is to establish a uniform bound on the iterates. We shall prove by induction that

$$(5.6) \quad |u_m(t+1)| \leq 7\alpha_1 t^{\operatorname{Re}(\delta_1)} e^{X_1 t}$$

for $t > t_0$, $m = 0, 1, 2, \dots$, and that

$$(5.7) \quad |u_m(t)| \leq 7\alpha_1 \alpha_2 t^{\operatorname{Re}(\delta_1)} e^{X_1 t}$$

for $t \geq t_0$, $m = 0, 1, 2, \dots$. α_1 and α_2 are the constants in equations (4.29)

and (4.30). The proof is just like the corresponding proof in §4 except that we must establish a suitable bound on $|D_p| = |D(u_p(t), u_p(t+1))|$. (5.6) and (5.7) certainly hold for $m=0$. Assume that they hold for $m=0, 1, \dots, p$. Then, from the definition of D ,

$$(5.8) \quad |D_p| \leq \sum_{i+j \geq 2} b_{ij} (7\alpha_1 \alpha_2 t^{\text{Re } (\delta_1)} e^{\mathbf{X}_1 t})^i (7\alpha_1 t^{\text{Re } (\delta_1)} e^{\mathbf{X}_1 t})^j.$$

We wish, first of all, to show that this series converges for $t \geq t_0$, provided

$$\max_{t_0 \leq t \leq t_0+1} |g(t)|$$

is sufficiently small. Now from equation (2.5) and the definition of $J(S_2, t_0)$ we see that $|J(S_2, t_0)| \leq C$, where C can be made as small as desired by taking $\max |g(t)|$ sufficiently small. Furthermore, by re-examining §2, we see that

$$|f(t-1, t_0)| = t^{-n} e^{-\mathbf{X}_2 t} \epsilon(t),$$

where the maximum of $|\epsilon(t)|$ for $t \geq t_0$ is small if $\max |g(t)|$ is small. It follows that in equation (4.29) α_1 is as small as desired if $\max |g(t)|$ is sufficiently small.

It follows that the series (5.8) is convergent for all $t \geq t_0$ if $\max |g(t)|$ is small enough. In fact,

$$(5.9) \quad |D_p| \leq \alpha_1 \alpha_5 (t^{\text{Re } (\delta_1)} e^{\mathbf{X}_1 t})^{3/2}$$

for $t \geq t_0$, where α_5 is small if $\max |g(t)|$ is small. Using (5.9) and the fact that α_5 may be taken as small as is required, we can complete the inductive proof of (5.6) and (5.7) just as in §4.

We show next that (5.5) defines a convergent sequence. The method is the same as that used in the preceding section. We shall first prove by induction that for $t > t_0$, $m=0, 1, 2, \dots$,

$$(5.10) \quad |u_{m+1}(t+1) - u_m(t+1)| t^{-\text{Re } (\delta_1)} e^{-\mathbf{X}_1 t} \leq \frac{14\alpha_1 \alpha_6^m t^{2m}}{m!}$$

for a certain constant α_6 . (5.10) is certainly true for $m=0$. Suppose that it has been proved for $m=0, 1, 2, \dots, p-1$. We consider the quantity

$$|D_p - D_{p-1}| = |D(u_p(t), u_p(t+1)) - D(u_{p-1}(t), u_{p-1}(t+1))|.$$

Note that because of the uniform bound on the approximations just established, the series D_p and D_{p-1} converge absolutely for $t \geq t_0$, provided $\max |g(t)|$ is sufficiently small. Now by the mean value theorem and the inequalities (5.6) and (5.7), we see that

$$|D_p - D_{p-1}| \leq C t^{\text{Re } (\delta_1)} e^{\mathbf{X}_1 t} \{ |u_p(t) - u_{p-1}(t)| + |u_p(t+1) - u_{p-1}(t+1)| \}.$$

By the assumption that (5.10) holds for $m=p-1$,

$$|D_p - D_{p-1}| \leq \frac{14C\alpha_1\alpha_0^{p-1}}{(p-1)!} t^{\operatorname{Re}(\delta_1)+2p-2} e^{X_1 t}.$$

The induction may now be completed as before.

Just as in §4, the inequality (5.10) shows that the sequence of approximations $u_0(t+1)$, $u_1(t+1)$, $\dots$ converges to a limit function $u(t+1)$ for $t > t_0$, and the convergence is uniform in any finite interval in which $t > t_0$. $u(t+1)$ is continuous for $t > t_0$, satisfies (5.4) for $t > t_0$, satisfies (5.2), and

$$(5.11) \quad |u(t+1)| \leq 7\alpha_1 t^{\operatorname{Re}(\delta_1)} e^{X_1 t}.$$

Finally, (5.11) enables us to prove, by the method used in proving (5.9), that

$$|D(u(t), u(t+1))| \leq C(t^{\operatorname{Re}(\delta_1)} e^{X_1 t})^{3/2}.$$

Consequently the integral

$$\int_{t_0}^{\infty} t_1 \{A(t_1)u(t_1) + B(t_1)u(t_1+1) + D(u(t_1), u(t_1+1))\} e^{-st_1} dt_1$$

is absolutely convergent for $\operatorname{Re}(s) > X_1$. We can therefore prove that $u(t)$ satisfies equation (5.1) for $t > t_0$ by retracing the steps of §3.

Next we shall prove that the function $u(t)$ constructed above by successive approximations is the unique solution of (5.1) and (5.2). Suppose that $v(t)$ is another solution, and that $v(t) = u(t)$ for $t_0 \leq t \leq T_0$ ($T_0 \geq t_0 + 1$), but that v and u are not equal in any larger interval. From (5.11), $|u(t)| \leq C_1$ for $t_0 \leq t \leq T_0 + 1$, where C_1 is as small as desired if $\max |g(t)|$ is sufficiently small. Since $u(t)$ and $v(t)$ are continuous, there is an ϵ , $0 < \epsilon < 1$, such that $|v(t)| \leq 2C_1$ for $t_0 \leq t \leq T_0 + \epsilon$. Hence $D(u(t), u(t+1))$ and $D(v(t), v(t+1))$ are absolutely convergent for $t_0 \leq t \leq T_0 - 1 + \epsilon$, and $|D(u(t), u(t+1)) - D(v(t), v(t+1))| \leq C_2 |u(t+1) - v(t+1)|$ for $t_0 \leq t \leq T_0 - 1 + \epsilon$. Now from equation (5.1) we see that u and v are both solutions of the integral equation

$$u(t+1) = g(t_0+1) + \int_{t_0}^t \{a(t_1)u(t_1) + b(t_1)u(t_1+1) + D(u(t_1), u(t_1+1))\} dt_1.$$

Consequently

$$(5.12) \quad |u(t+1) - v(t+1)| \leq C_3 \int_{T_0-1}^t |u(t_1+1) - v(t_1+1)| dt_1$$

for $T_0 - 1 \leq t \leq T_0 - 1 + \epsilon$. But $|u(t_1) - v(t_1)| \leq 4C_1$ for $T_0 \leq t_1 \leq T_0 + \epsilon$. It follows from iteration in (5.12) that $u(t) = v(t)$ for $T_0 \leq t \leq T_0 + \epsilon$. This contradicts our original assumption. Therefore the solution $u(t)$ is unique.

The proof of Theorem 1.3 is now complete.

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